Productivity Inc



Productivity Pre-Engineered Systems LOWER initial investment. SHORTER lead times. PREDICTABLE results.

System Options



Quick-Change Gripper Mount allows the operator to change gripper head assemblies in seconds.



Part Re-Grip Station provides a quick change base that can accommodate a variety of small fixtures a robot may require in dual sided operations.



Door Actuator allows the robot to automatically open and close the machine door. There are several models based upon your configuration.



iRVision Robotic Vision System allows operators to randomly place parts onto the infeed device.



Part Inspection Chute allows the robot to place parts external to the robot These can be used for mass part collection or to handle in-process inspection.



Workholding options are available. Please discuss your needs with your sales specialist.

Pre-Engineered CNC Machine Tending Robotic Systems



Material Closet Key Features

- 20 tray system
- Multi-machine layouts possible (bigger robot)
- Can hold 15 lbs per tray
- 30 square feet of queue
- Small floor footprint

RoboFlex MC Base Package

Popular Options

(others by consultation)

- FANUC iRVision 2D part locating system
- · Re-grip/flip station
- Part inspection/exit chute
- Pneumatic vertical sliding shutter
- · Fast servo (2) door shutter
- High-speed servo door actuator
- Upgrade to quick-change tool stem
- Extra guick-change dual gripper assembly
- · Additional machine integration
- Vise mount casting for rotary table (8")
- Schunk KSP 160 Plus vise



Machine Interface provides electrical connection of each machine tool to the robot. Only one is included. Each machine tool needs



Gripper Head Assembly can be provided if you want to have your cell be quickly changed over in multi-part operations.

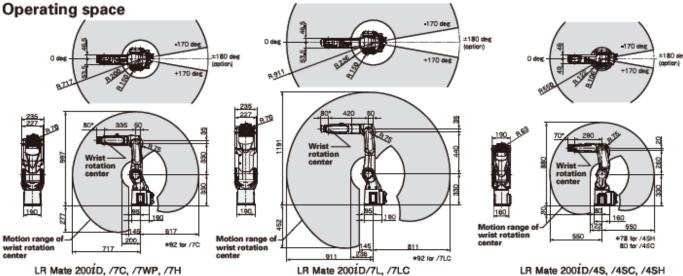
Versatile Intelligent Mini Robot

Features

The LR Mate 200 i D is a compact six-axis mini robot with the approximate size and reach of a human arm.

- Slim arm minimizes interference to peripheral devices and allows operation in narrow spaces.
- · Standard arm (717mm reach), short arm (550mm reach), long arm (911mm reach), food/cleanroom, wash-proof and 5-axes high speed models are available.
- Lightest mechanical unit in its class enables easy system integration and installation flexibility with multiple mounting methods.
- The most advanced servo technology and highly rigid arm enable smooth motion without vibration in high-speed operations.
- · Enhanced wrist load capacity allows for greater efficiency and the ability to handle multiple worknieces
- · Vision and force sensor cables (option), auxiliary axis cable (option - limited model types), solenoid valve, air tube and I/O cable for device control are integrated into the arm for easy cable handling.
- · IP69K (robot option limited model types) provides enhanced dust and water protection in harsh environments. Available bottom cable exit (option) also protects cable from harsh environments.
- High performance R-301B Mate controller has two types - standard enclosed controller that enables reliable operation under a factory environment with dust and oil mist, and compact controller for clean environment.
- · Various intelligent features are available as an option, such as *i* RVision (integrated vision) and force sensing.

FANUC Robot LR Mate 2001D



Specifications

Specificat	10115					
Model		LR Mate 200 D LR Mate 200 D/7C LR Mate 200 D/7WP	LR Mate 200(D/7H	LR Mate 200 D/7L LR Mate 200 D/7LC	LR Mate 200 D/4S LR Mate 200 D/4SC	LR Mate 200 D/4SH
Controlled axes		6 axes	5 axes	6 axes	6 axes	5 axes
Reach		717 mm		911 mm	550 mm	
Installation (Note 2)		Floor, Upside-down, Angle mount				
Motion range (Maximum speed)	J1 axis	340°/360°(option) (450°/s) 5.93 rad/6.28 rad (option) (7.85 rad/s)		340°/360°(option) (370°/s) 5.93 rad/6.28 rad (option) (6.46 rad/s)	340°/360°(option) (460°/s) 5.93 rad/6.28 rad (option) (8.03 rad/s)	
	J2 axis	245°(380°/s) 4.28 rad (6.63 rad/s)		245°(310°/s) 4.28 rad (5.41 rad/s)	230°(460°/s) 4.01 rad (8.03 rad/s)	
	J3 axis	420°(520°/s) 7.33 rad (9.08 rad/s)		430°(410°/s) 7.50 rad (7.16 rad/s)	402°(520°/s) 7.02 rad (9.08 rad/s)	
	J4 axis	380°(550°/s) 6.63 rad (9.60 rad/s)	250°(545°/s) 4.36 rad (9.51 rad/s)	380°(550°/s) 6.63 rad (9.60 rad/s)	380°(560°/s) 6.63 rad (9.77 rad/s)	240°(560°/s) 4.19 rad (9.77 rad/s)
	J5 axis	250°(545°/s) 4.36 rad (9.51 rad/s)	720°(1500°/s) 12.57 rad (26.18 rad/s)	250°(545°/s) 4.36 rad (9.51 rad/s)	(Note 6) 240°(560°/s) 4.19 rad (9.77 rad/s)	720°(1500°/s) 12.57 rad (26.18 rad/s
	J6 axis	720°(1000°/s) 12.57 rad (17.45 rad/s)		720°(1000°/s) 12.57 rad (17.45 rad/s)	720°(900°/s) 12.57 rad (15.71 rad/s)	
Max. load capacity at wrist		7 kg			4 kg	
Allowable load moment at wrist	J4 axis			N·m	8.86 N-m	
	J5 axis	16.6 N-m	4.0 N·m 5.5 N·m (option)	16.6 N·m	8.86 N·m	4.0 N-m 5.5 N-m (option)
	J6 axis	9.4 N·m		9.4 N-m	4.90 N·m	
Allowable load inertia at wrist	J4 axis			kg-m²	0.20 kg-m²	
	J5 axis	0.47 kg-m ²	0.046 kg·m² 0.15 kg·m² (option)	0.47 kg·m²	0.20 kg·m²	0.046 kg·m² 0.083 kg·m² (option)
	J6 axis	0.15 kg·m²		0.15 kg-m²	0.067 kg-m ²	
Repeatability		± 0.02 mm		± 0.03 mm	± 0.02 mm	
Mass (Note 3)		25 kg	24 kg	27 kg	20 kg	19 kg
Installation environment		Ambient temperature: 0~45°C Ambient humidity: Normally 75%RH or less (No dew nor frost allowed) Short term: 95%RH or less (within one month) Vibration acceleration: 4.9m/s² (0.5G) or less				

Note 1) In case of short distance motion, the axis speed may not reach the maximum value stated.

Note 2) Angle mounting needs J1 and J2 axis motion range restriction according with the payload, except for LR Mate 200/D/4S, /4SC and /4SH.

Note 3) Without controller.

Note 4) The liquids that deteriorate the sealing members, such as organic solvents, acids, alkalis, and chloric coolants, must not be used. Note 5) Cleanliness of the clean type (/7C, /7LC, /4SC) is class 10 (ISO class 4) with white paint, antirust surface and food grade grease.

Note 6) In case of /4SC, J5 motion range is restricted to 236° (4.11rad).

